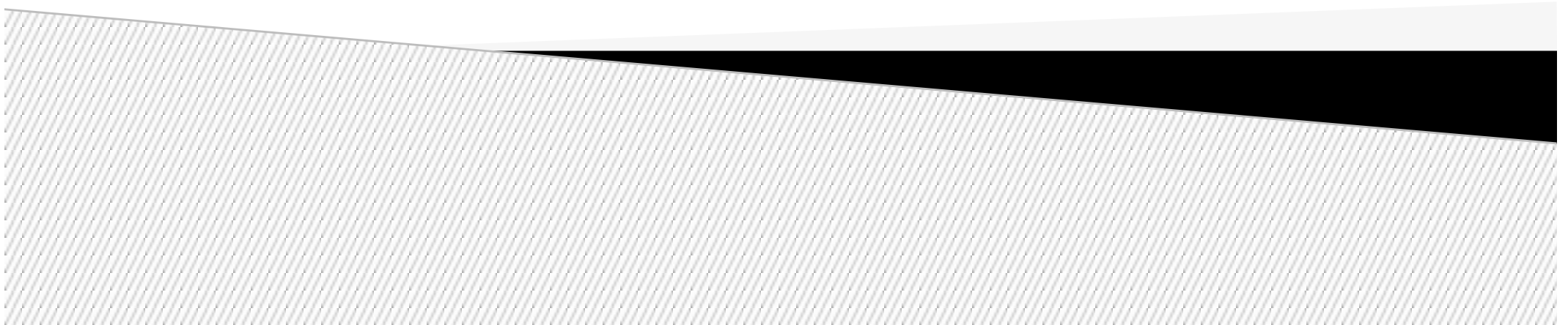


Material representation, Reflectance, BRDFs

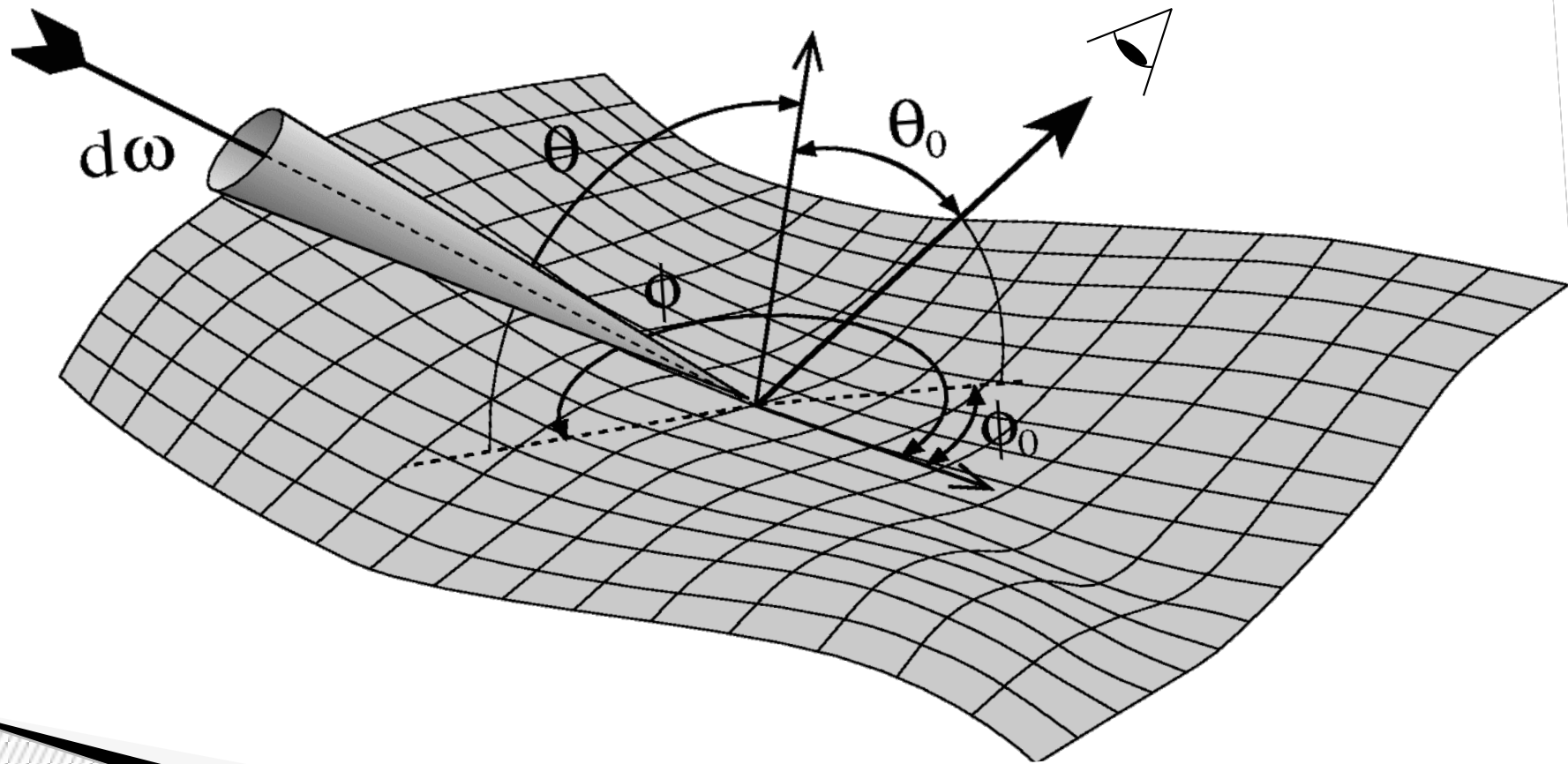


Local illumination models

- ▶ A single point light source
- ▶ Linear combination for several light sources
 - $I(a+b) = I(a)+I(b)$
 - $I(s \cdot a) = s \cdot I(a)$
- ▶ No interactions between objects
 - No shadows, no reflections
- ▶ Computing color independently for each pixel

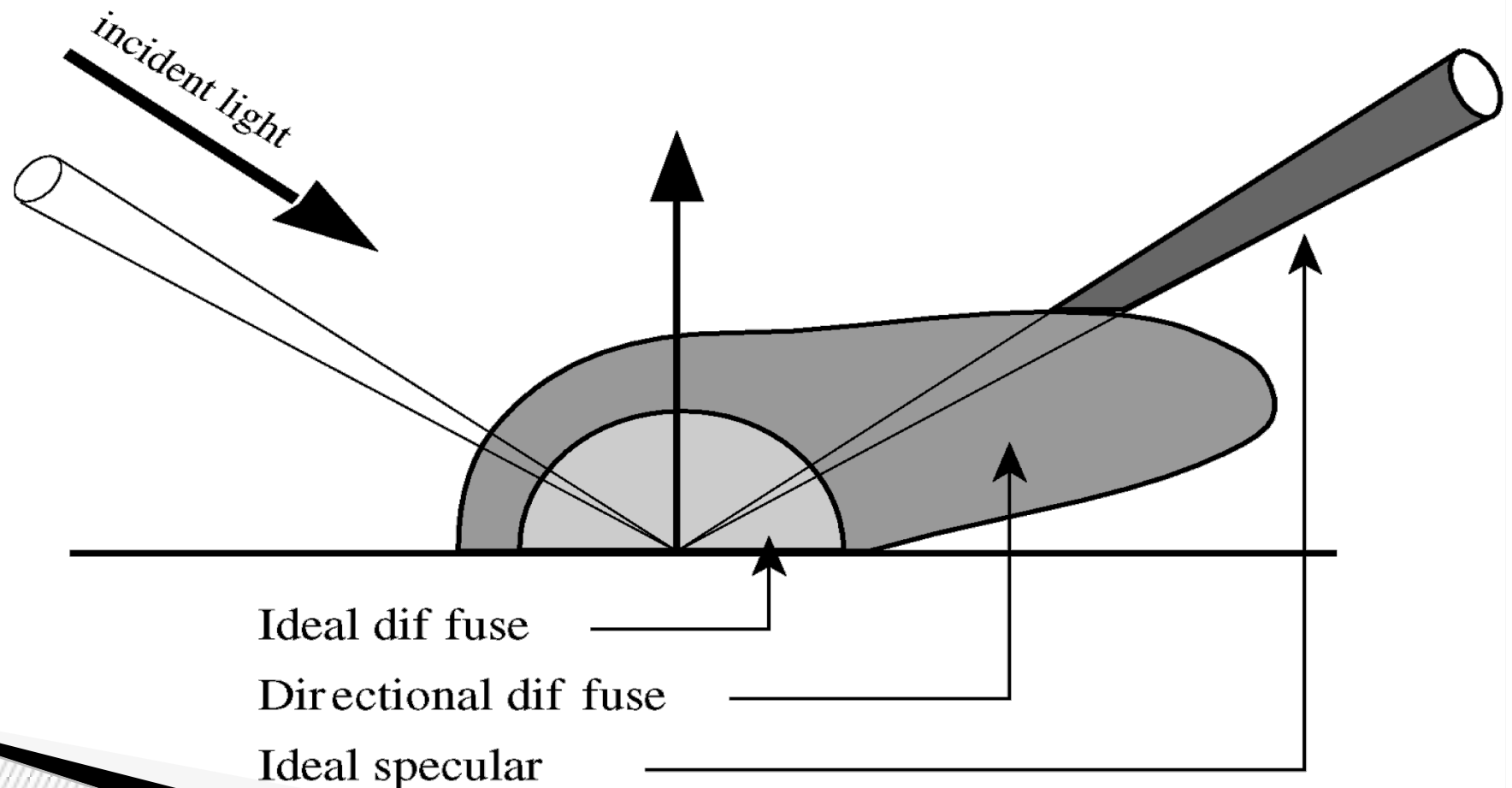
BRDF: Bi-directional Reflectance Distribution Function

- ▶ 4D Function: $f(\theta, \phi, \theta_0, \phi_0)$, tells how the light is reaching a point is reflected



BRDF

- Ratio between incoming light and outgoing light
- Complete description of the behaviour of the material at each point, for every incoming and outgoing direction



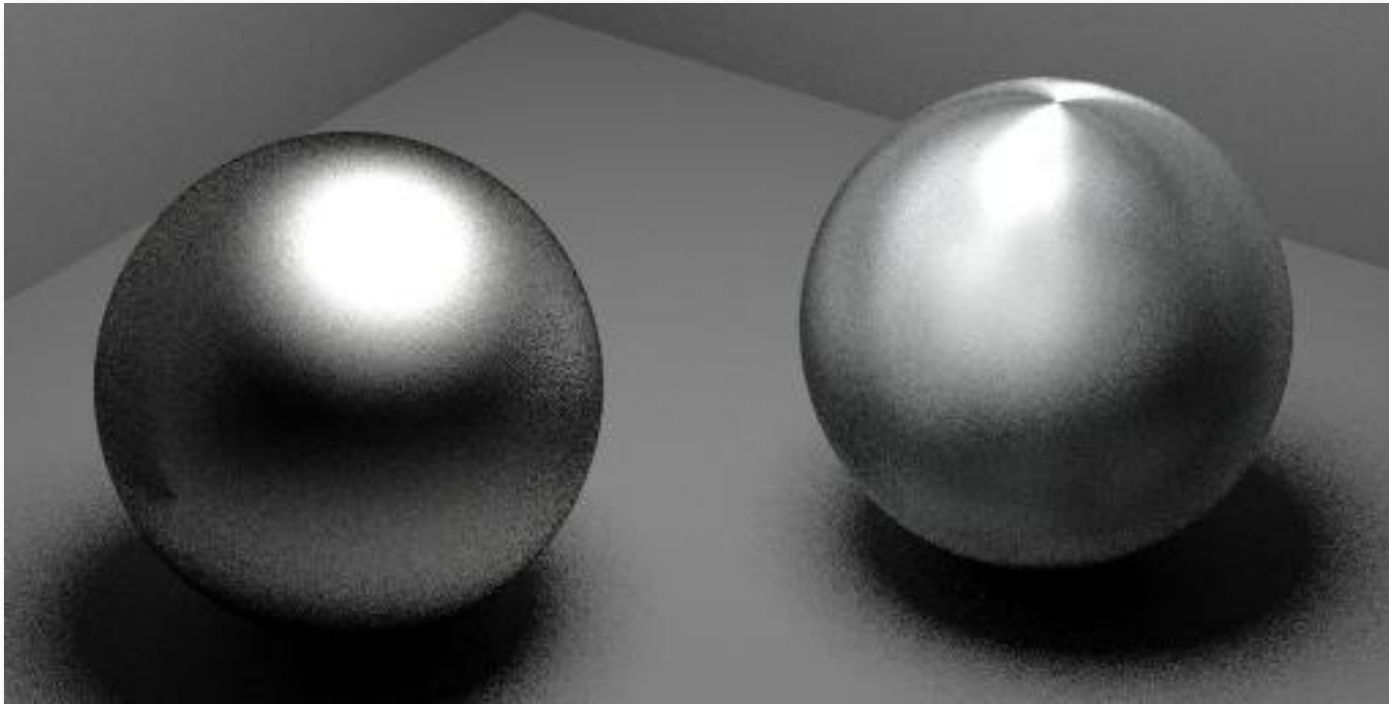
BRDF – Isotropic vs. anisotropic?

▶ Isotropic

- Rotationally invariant (3D)
- True for many materials
- One dimension less

▶ Anisotropic

- Depends on the angle of rotation around the surface normal

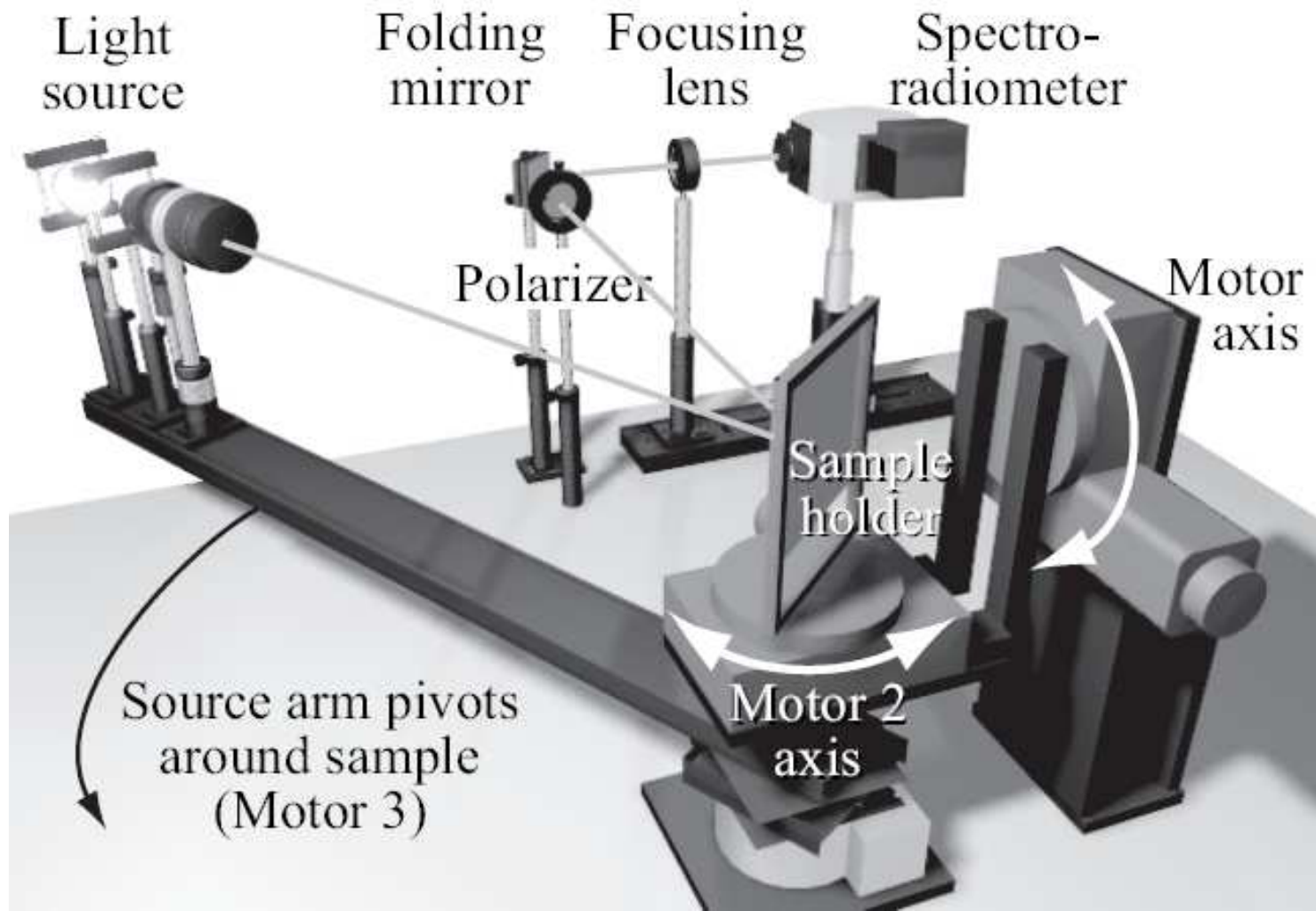


BRDF – Representation

- ▶ Constraints:
 - Storage space
 - Accurate representation of the properties of a material
 - Fast and easy sampling
- ▶ 2 solutions:
 - **Explicit storage** of measured data
 - Approximation through an **analytical model**

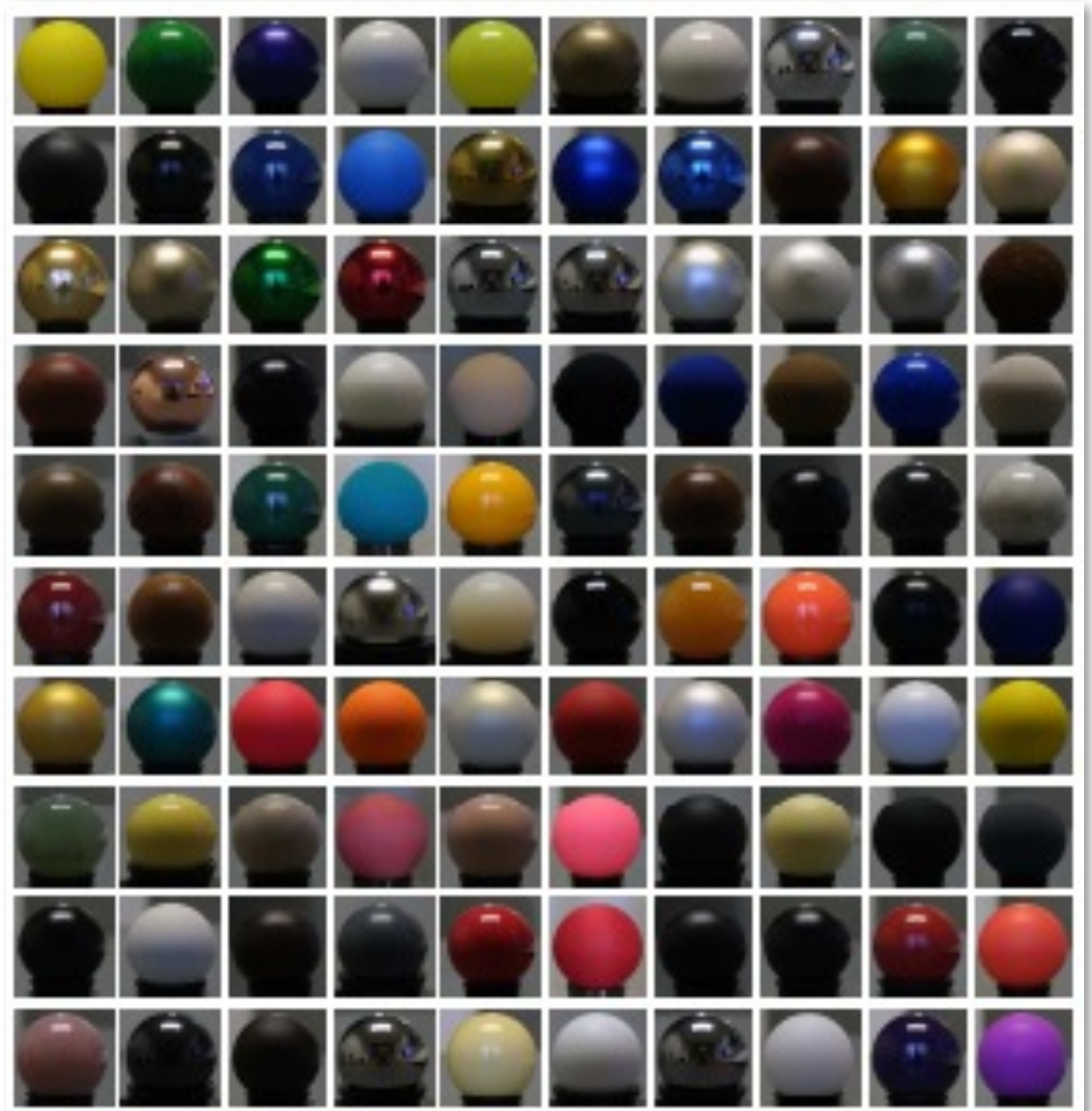
BRDF – Acquisition

- ▶ Acquisition system: gonioreflectometer



BRDF - Database

- ▶ MERL dataset
 - 100 measured materials



BRDF– Analytical models

▶ Empirical

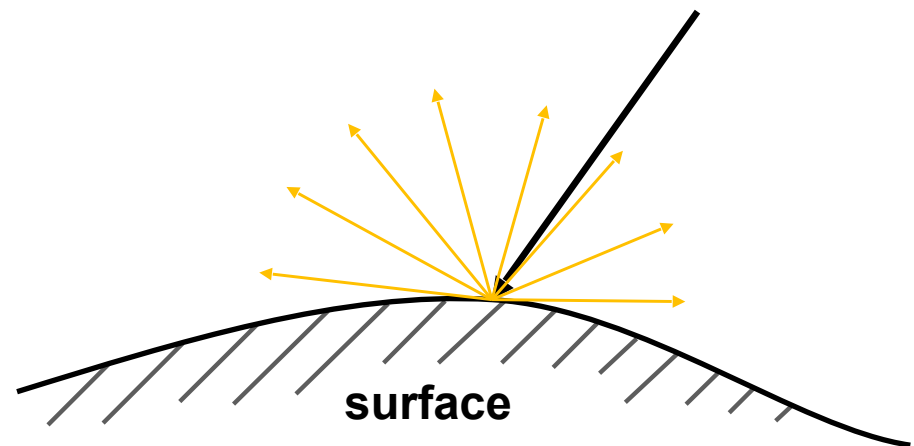
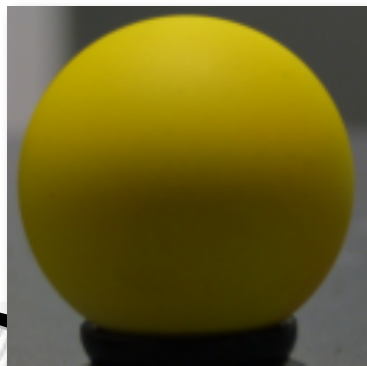
- Lambert, Phong, Blinn, Ward, Lafortune
- Can be combined for increased realism
- Easy to use

▶ Physically based models

- Torrance–Sparrow, Cook–Torrance, Kajiya...
- Need information on the material (roughness...)

Ideal diffuse reflection

- ▶ Diffuse reflexion
 - Object reflecting light uniformly in all directions
- ▶ **Lambertian** surfaces (mate: chalk, paper)
 - Intensity at one point: only depends on the angle between incoming light and surface normal
- ▶ Uniform BRDF



Diffuse reflection



increasing ρ_d

$$I = \rho_d \cos \theta$$

Ambiant light

- ▶ Trick for better visual realism
- ▶ No relation with physical realism
- ▶ Light independent from position:

$$I = \rho_a I_a$$

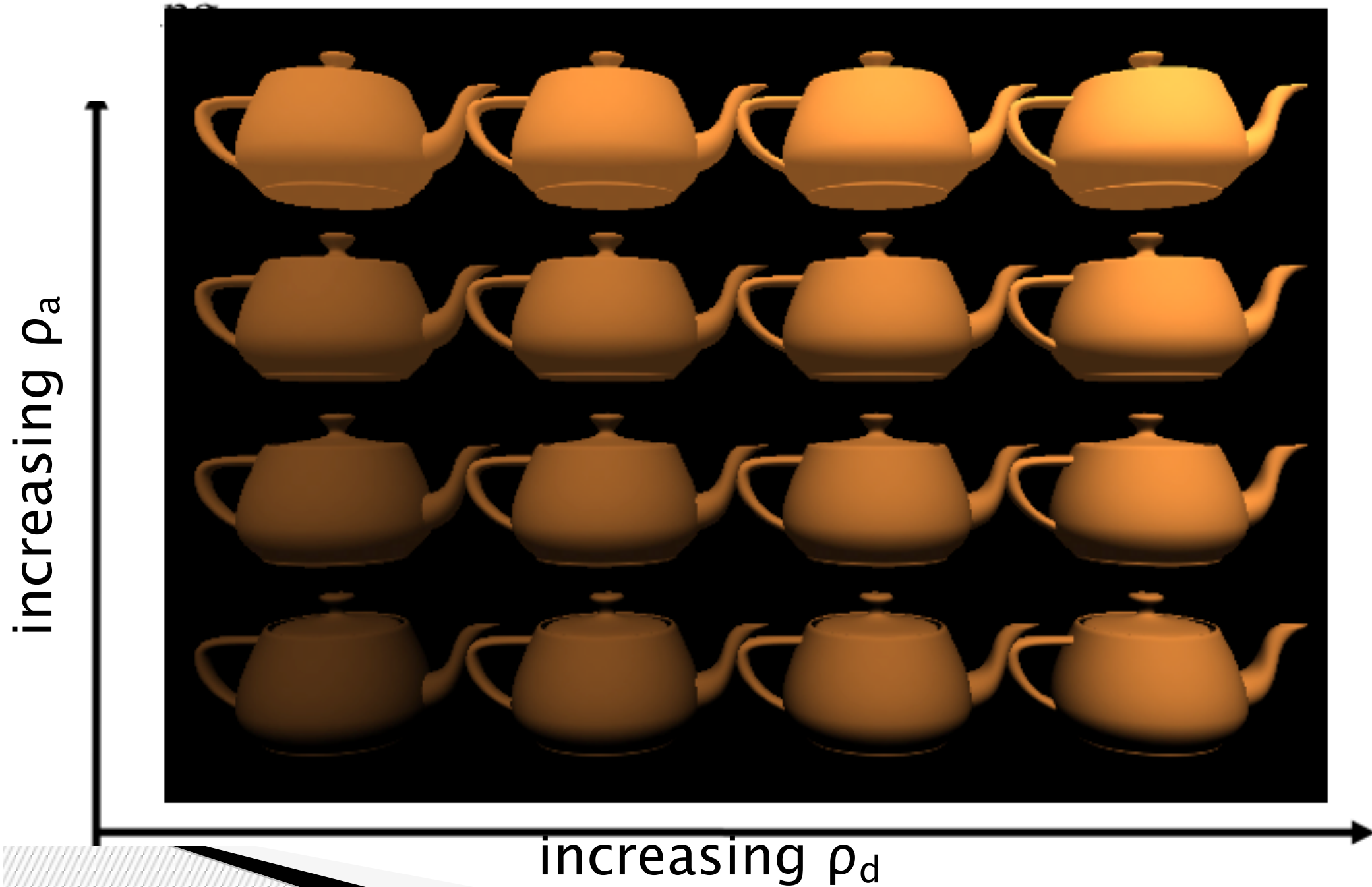
- ▶ Very simple model:
 - ▶ no visible 3D effect
 - ▶ useful to hide some defects

Ambient light



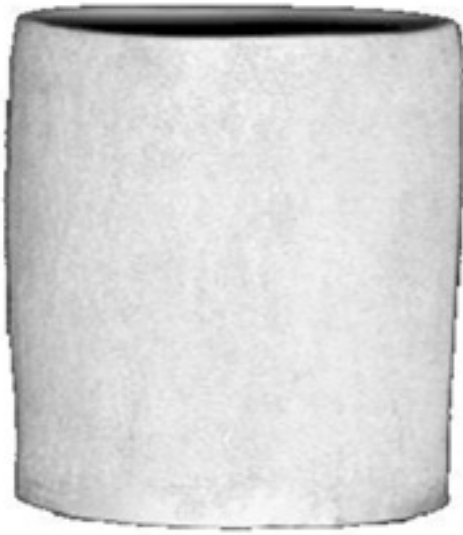
increasing ρ_a

Diffuse + ambient



Oren-Nayar model [1993]

- ▶ rough diffuse materials



Photograph



Diffuse model



Oren-Nayar

Ideal specular reflection

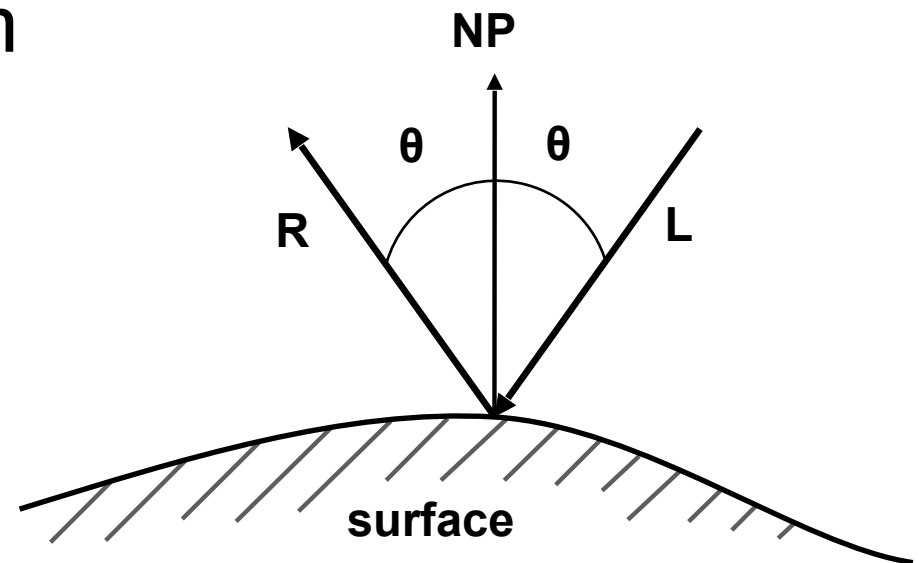
- ▶ **Specular reflection**

- Smooth, shiny surfaces (mirrors, metals)

- ▶ **Snell / Descartes law**

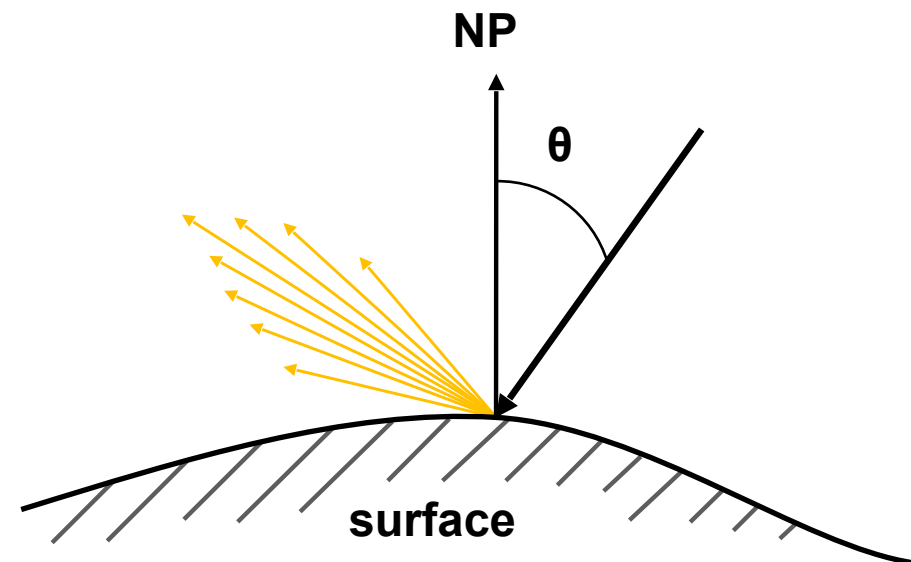
- Light reaching a point reflected in the direction having the same angle with the normal

- ▶ **BRDF: Dirac distribution**



Non-ideal specular reflection

- ▶ Problem: ideal specular reflection limited
 - Useful for indirect lighting
 - Less so for direct lighting with point light sources
 - Assumes perfectly smooth surfaces
- ▶ Phong model
- ▶ Fresnel coefficients

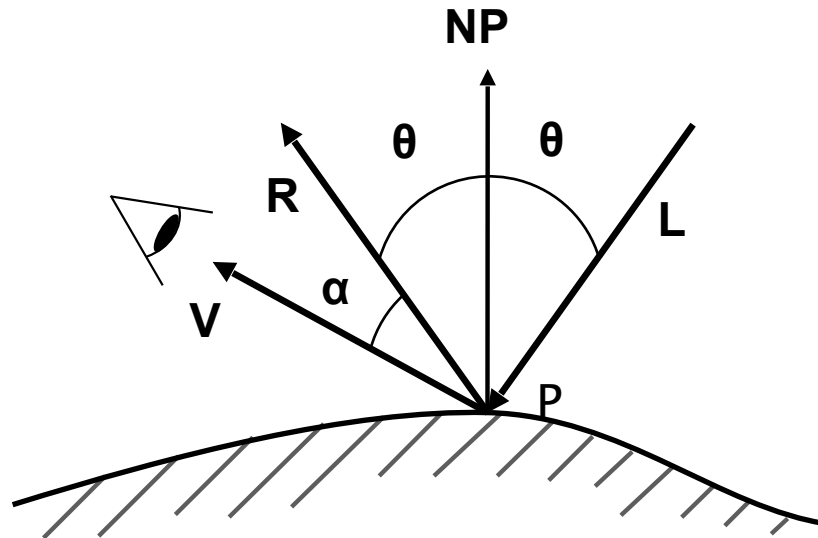


Phong model [1975]

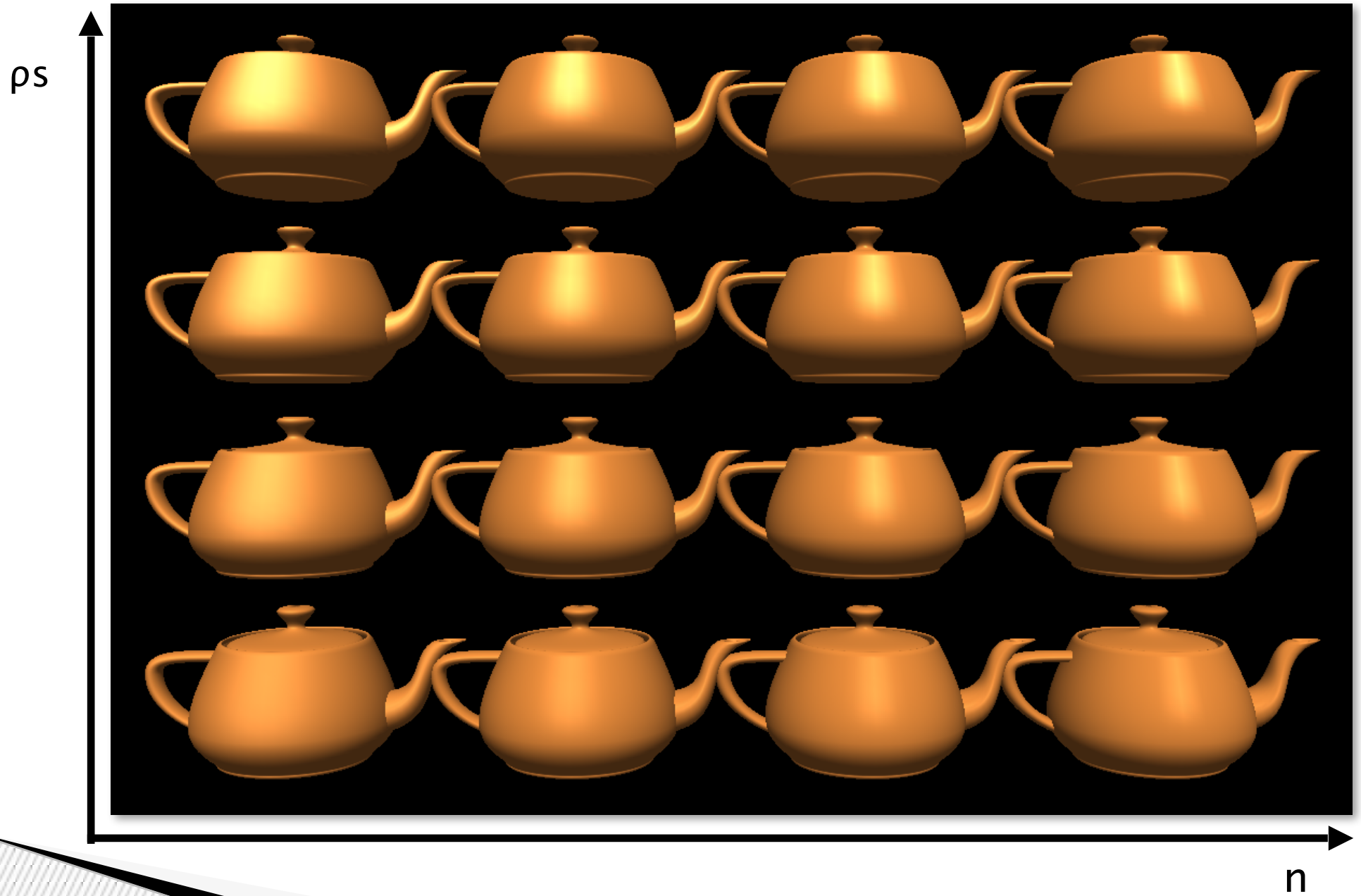
- ▶ Intensity varying with angle α between viewing direction V and reflected direction R
(R symmetric of L w.r.t. the normal)

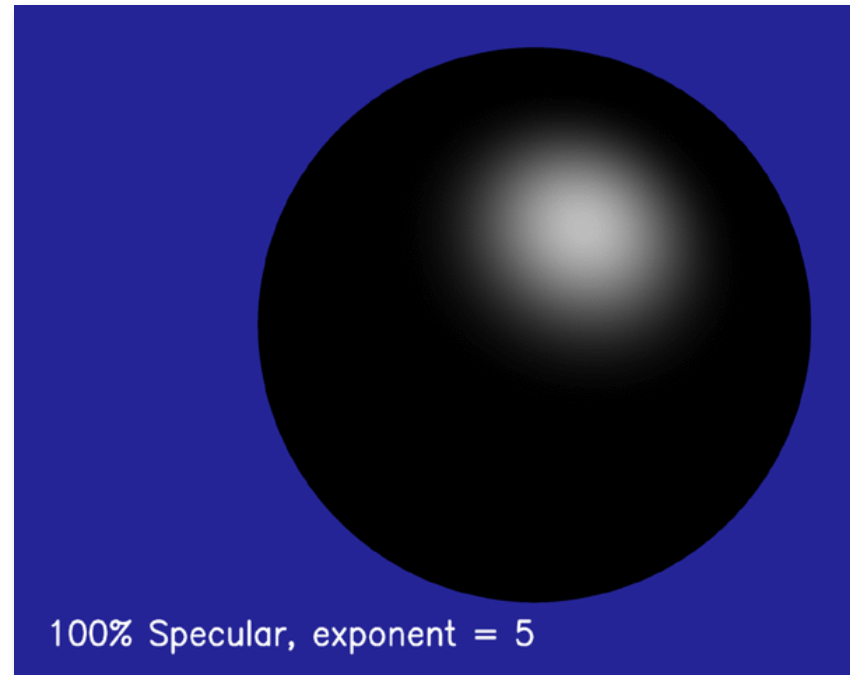
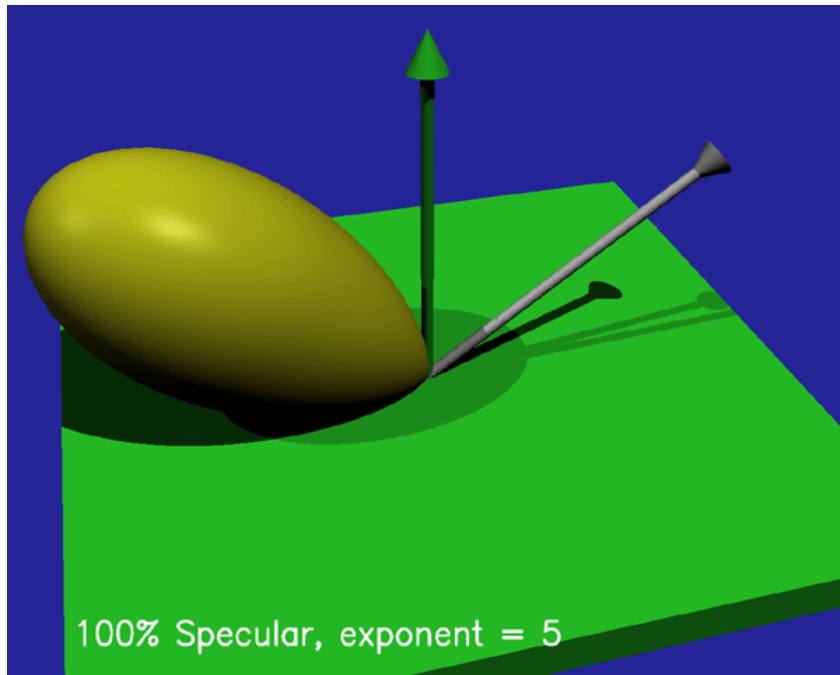
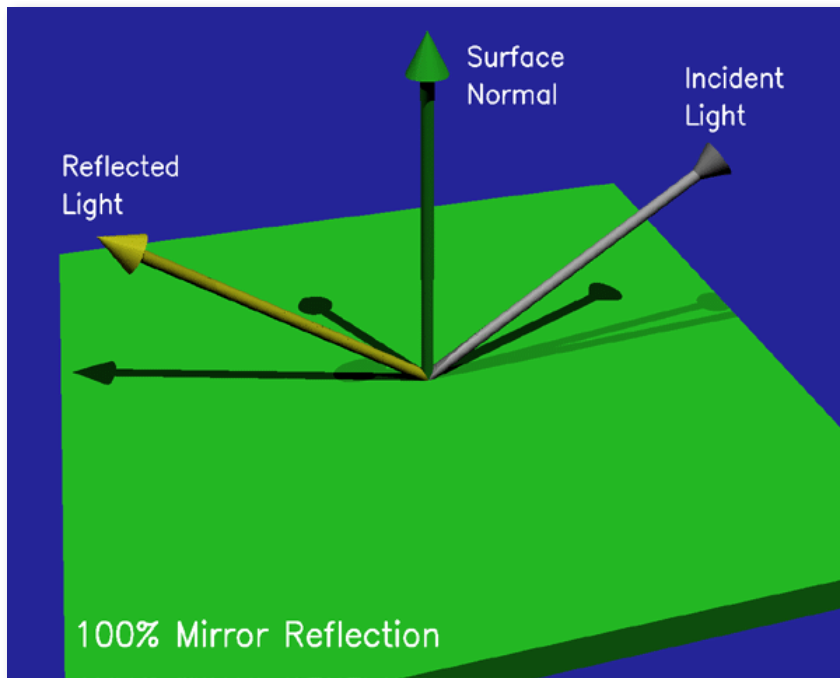
$$I(P) = \rho_s L \cos^s \alpha$$

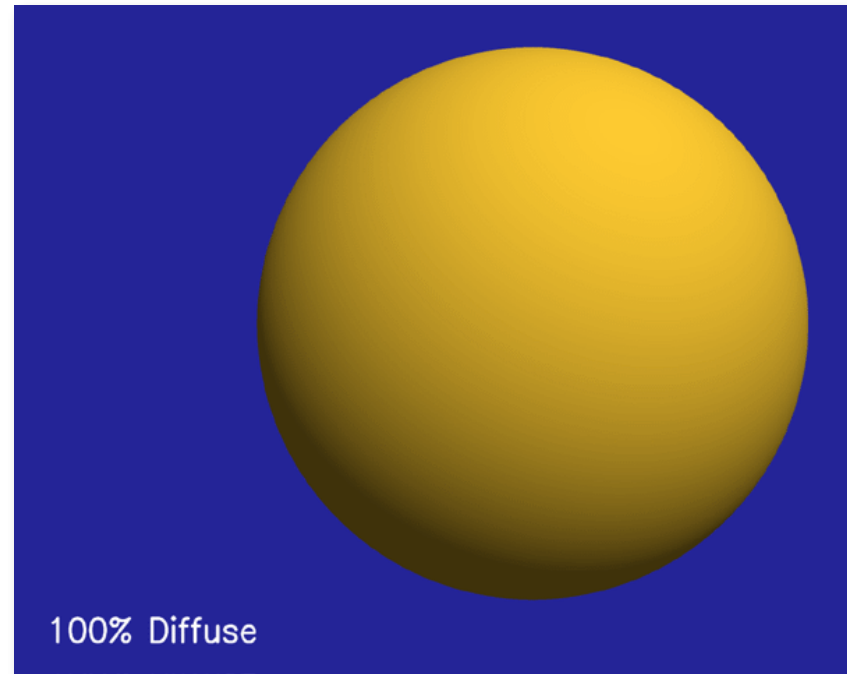
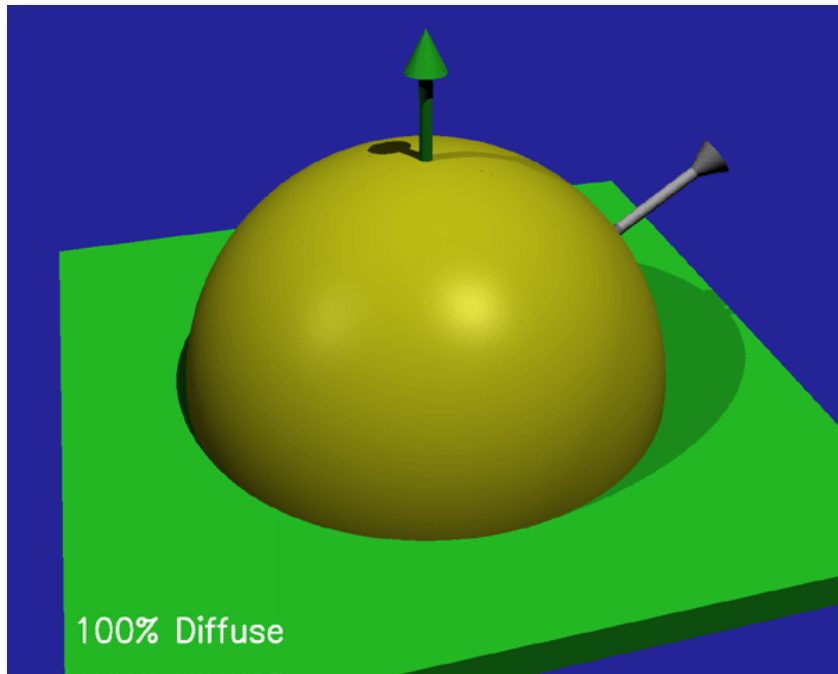
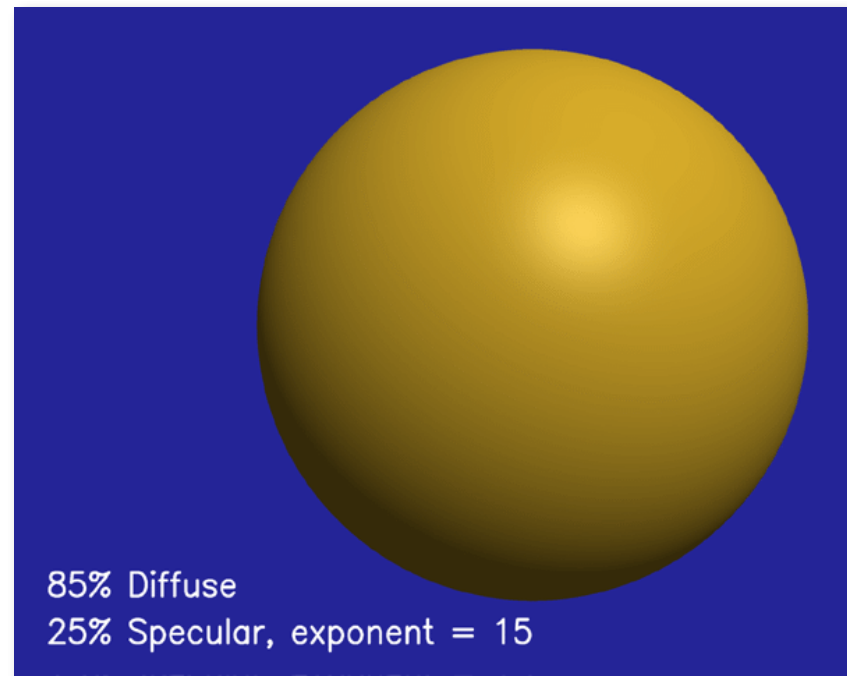
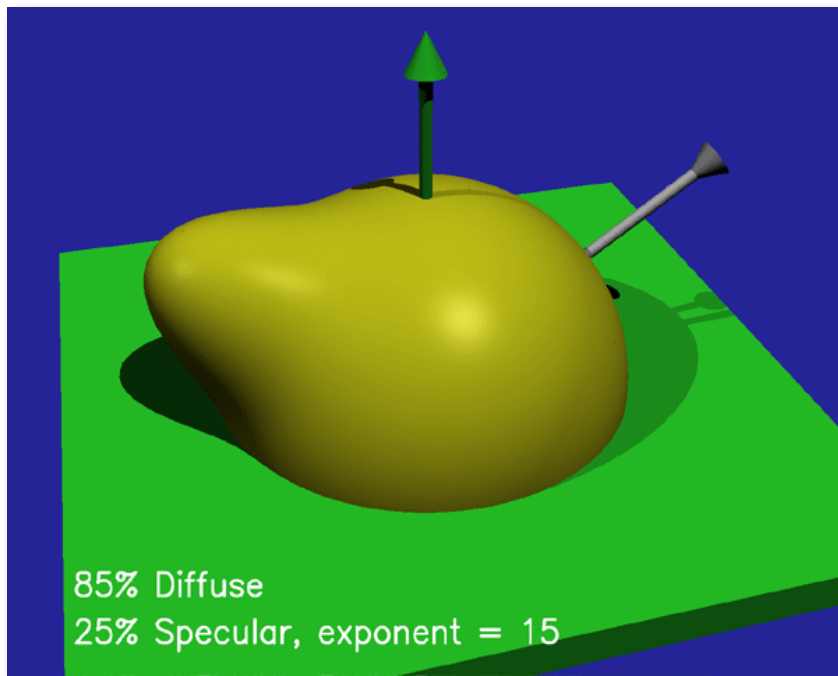
- s = roughness: ∞ (1024) for a mirror, 2-3 for rough surface
- $\cos \alpha = V \cdot R$
- $R = 2(\cos\theta) N - L$
 $= 2(N \cdot L) N - L$

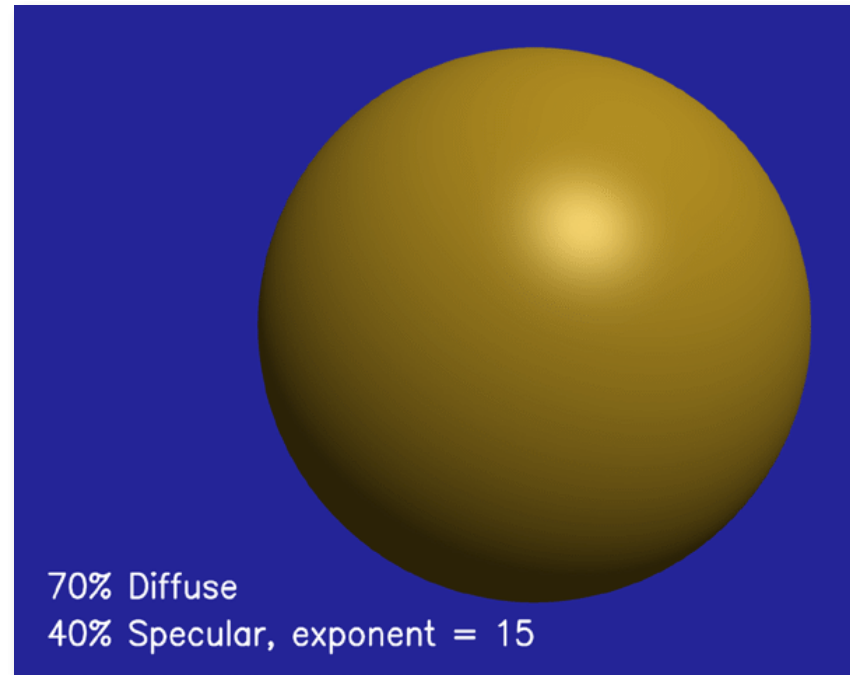
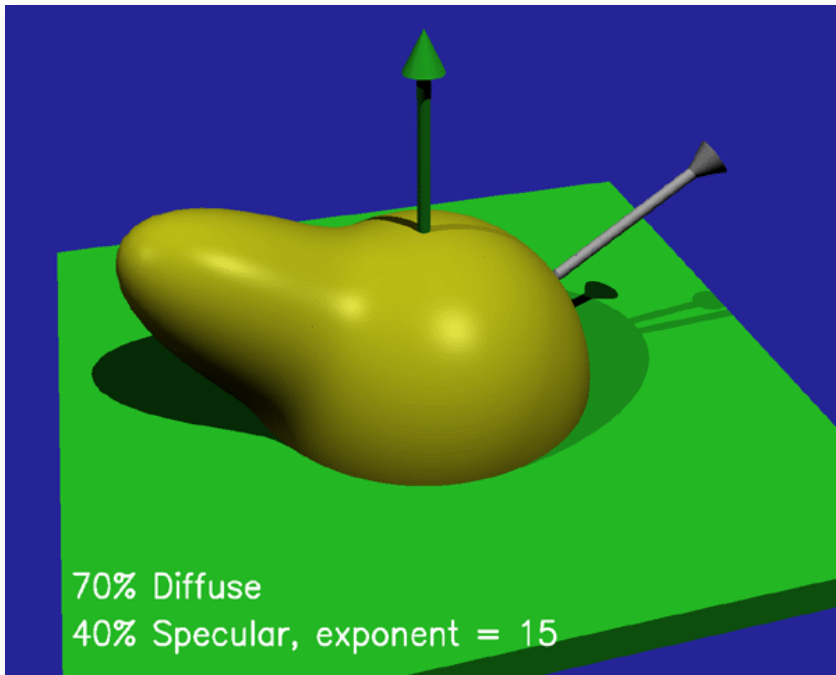
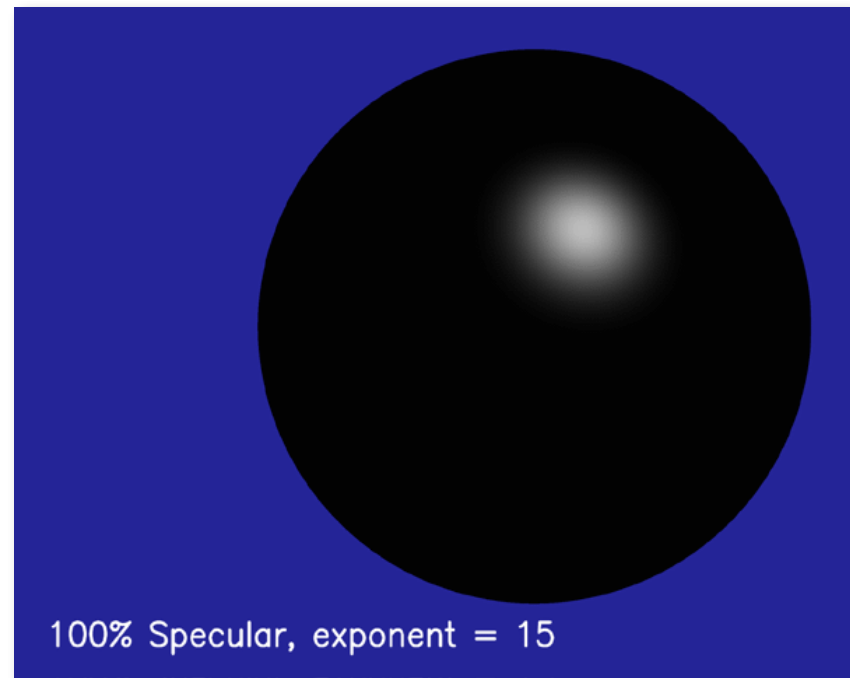
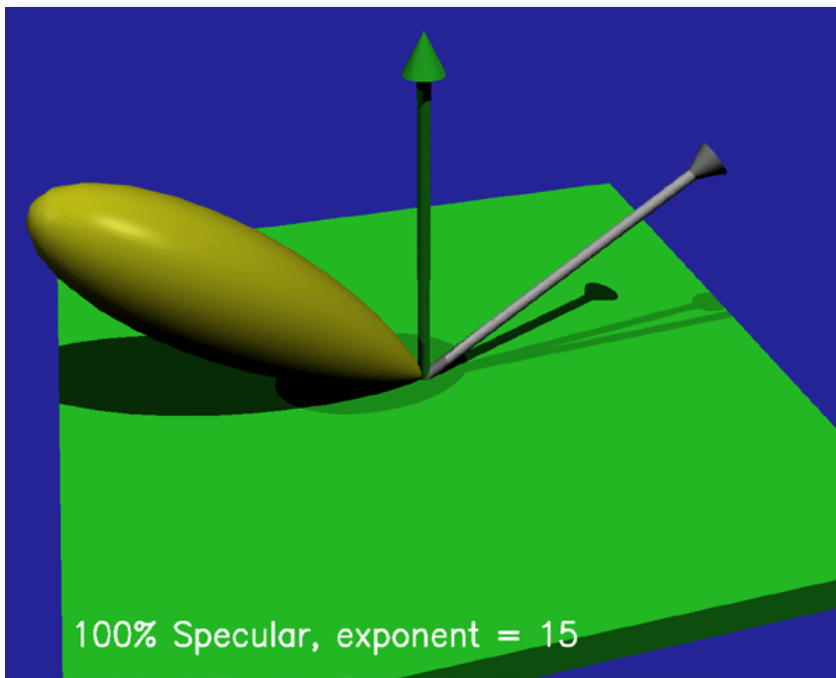


Phong model



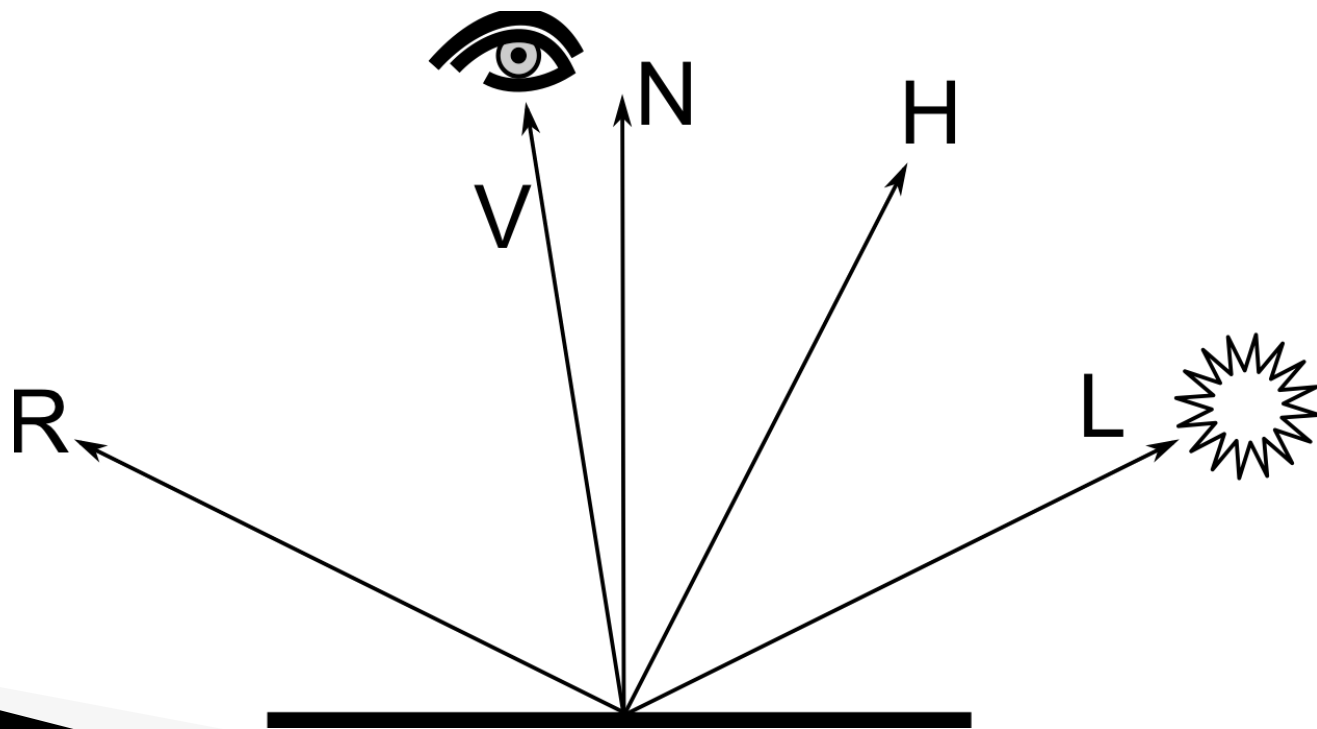






Blinn-Phong model [1977]

- ▶ Uses the half-vector: $\mathbf{h} = \frac{\mathbf{l} + \mathbf{v}}{\|\mathbf{l} + \mathbf{v}\|}$
- ▶ Reflected light is now: $I = \rho_s (\cos \theta)^n = \rho_s (\mathbf{h} \cdot \mathbf{n})^n$



Blinn-Phong or Phong

- ▶ Visually very similar
 - assuming you use $n = 4s$
 - slight differences for grazing directions
 - symmetric lobes for Phong, asymmetric for Blinn
- ▶ Blinn-Phong easier to code (?) (YMAMV)

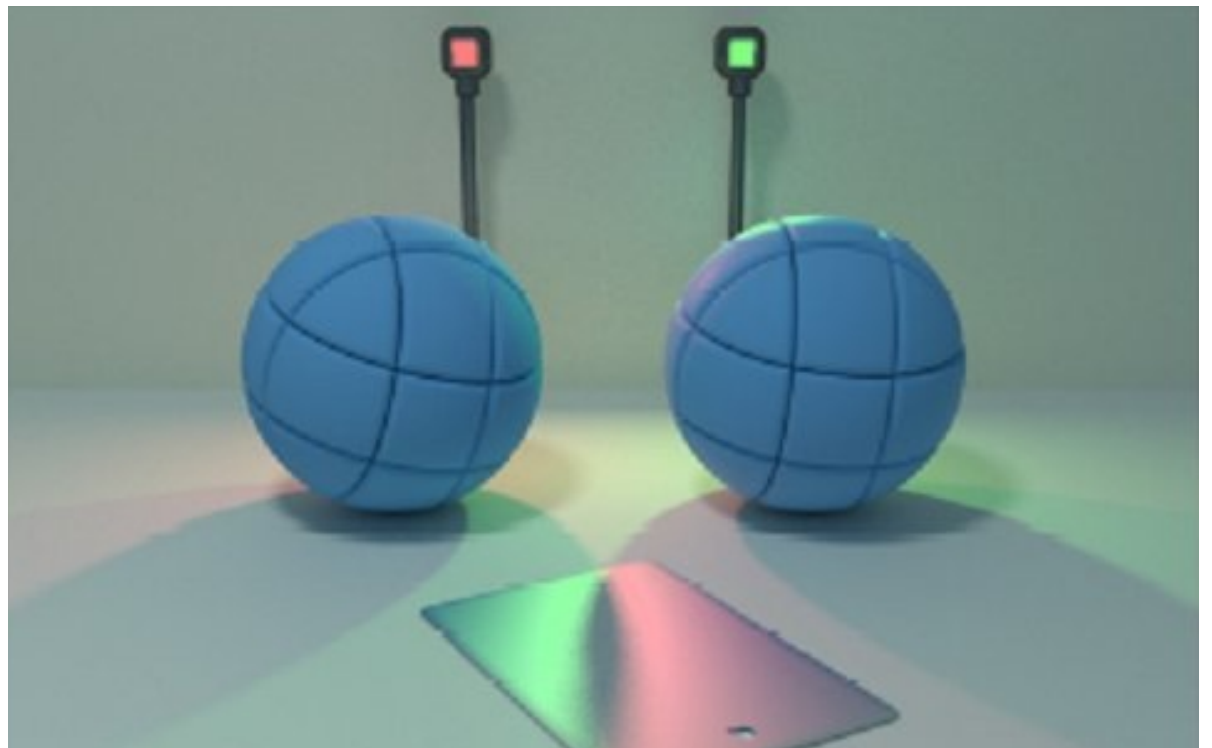
Lafortune Model

- ▶ “Improved Phong”
- ▶ “Perturb” the reflected direction vector

$$K = \rho_s \cdot [C_{xy}(l_x v_x + l_y v_y) + C_z l_z v_z]^n$$

$$\mathbf{l} = (l_x, l_y, l_z)$$

$$\mathbf{v} = (v_x, v_y, v_z)$$



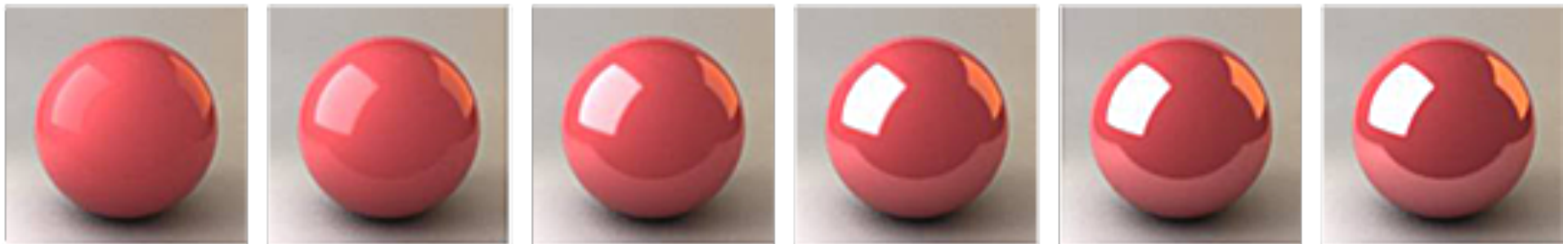
Fresnel coefficients



Experiment by Lafortune, Foo, Torrance & Greenberg (Siggraph 1997)

Fresnel Coefficients

- ▶ Reflection coefficients varying with viewing angle
- ▶ Interface between 2 materials, with different index:
 - complex (metals)
 - real (transparent / dielectric)



Fresnel Coefficients

- ▶ Depends on material index, polarization
- ▶ Complicated formula

$$R_p = \left(\frac{n_1 \cos \theta_t - n_2 \cos \theta_i}{n_1 \cos \theta_t + n_2 \cos \theta_i} \right)^2 \quad R_s = \left(\frac{n_1 \cos \theta_i - n_2 \cos \theta_t}{n_1 \cos \theta_i + n_2 \cos \theta_t} \right)^2$$

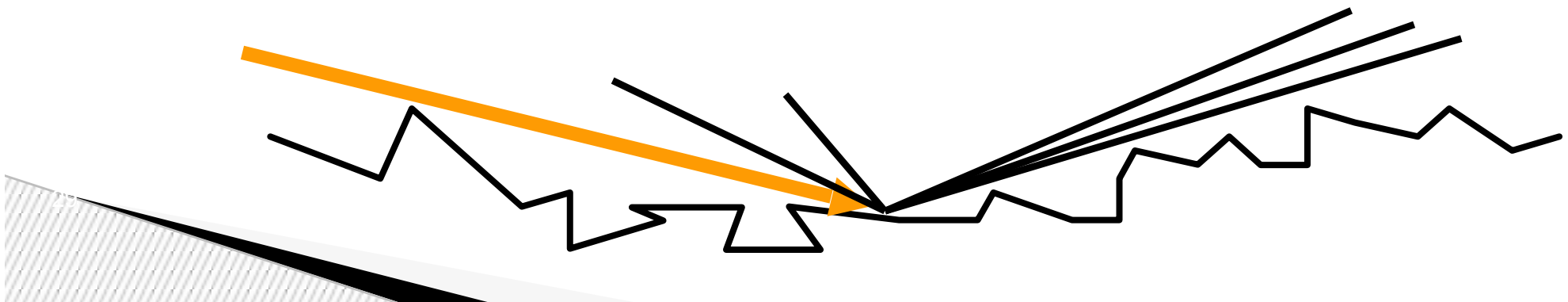
- ▶ Schlick Approximation:

$$F = F_0 + (1 - F_0)(1 - \cos \theta)^5$$

$$\cos \theta = (\mathbf{v} \cdot \mathbf{h})$$

Cook-Torrance-Sparrow model [1967]

- ▶ Surface is made of micro-facets
 - small specular mirrors
- ▶ Light reaching a facet:
 - Reflected, masked, shadowed
 - Statistical analysis, depending on micro-facets orientation probability distribution
 - A bit more complex. Good approximation.



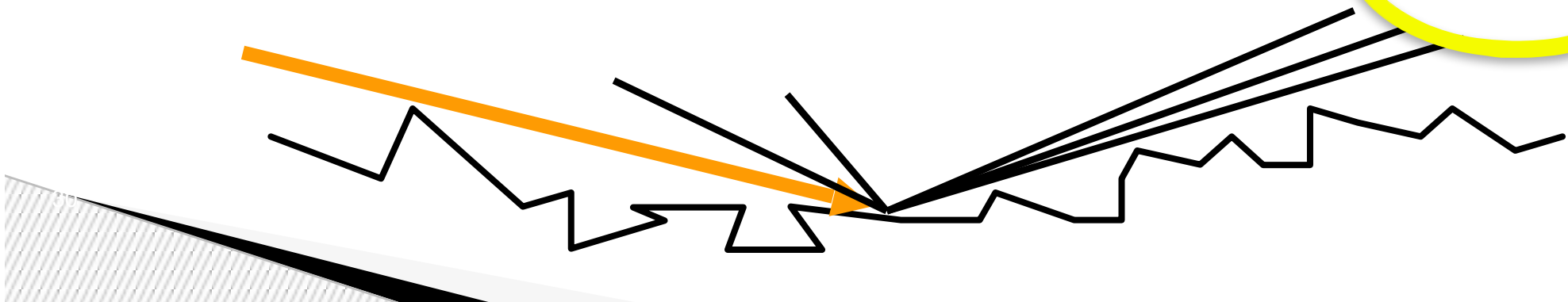
Cook-Torrance-Sparrow Model [1967]

- ▶ Product of 3 terms
 - Fresnel coefficient (F)
 - Distribution of facets orientation (D)
 - Masking and shadowing (G)

$$K = \frac{\rho_s}{\pi} \frac{DG}{(N \cdot L)(N \cdot V)} \text{Fresnel}(F_0, V \cdot H)$$

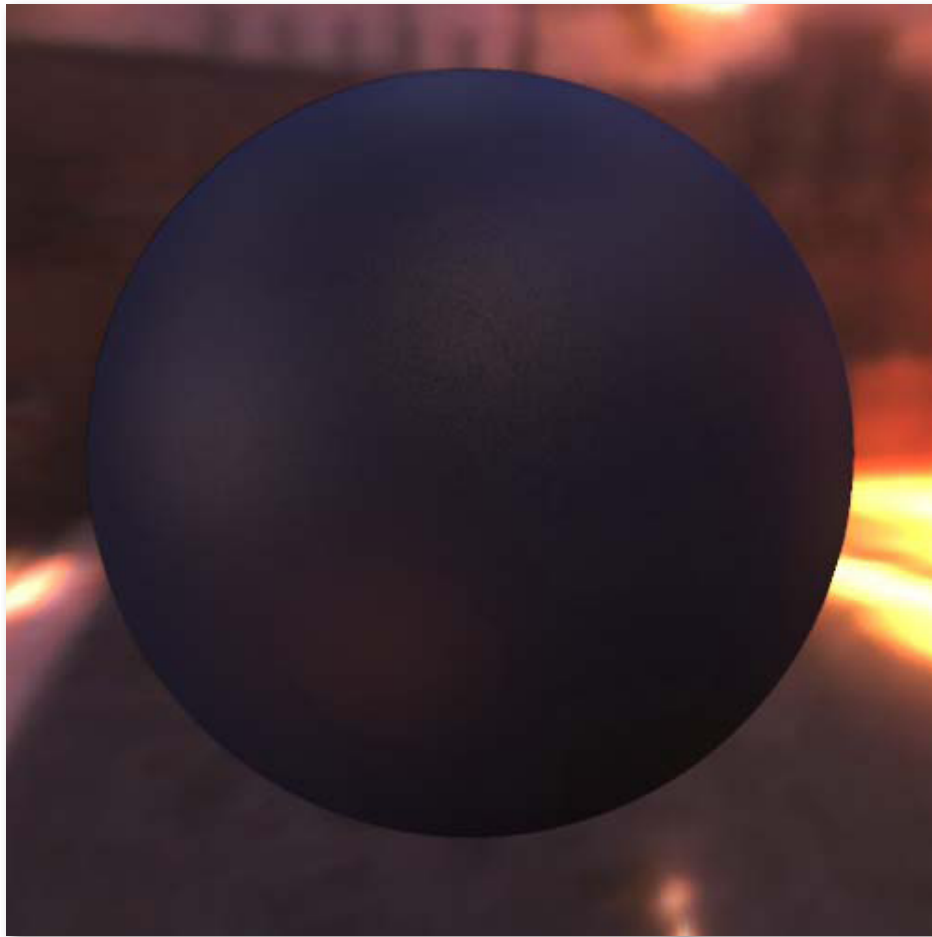
A gaussian distribution!

$$G = \min\left\{1, \frac{2(N \cdot H)(N \cdot V)}{(V \cdot H)}, \frac{2(N \cdot H)(N \cdot L)}{(V \cdot H)}\right\} \text{ and } D = \frac{1}{m^2 \cos^4 \delta} e^{-[(\tan \delta)/m]^2}$$

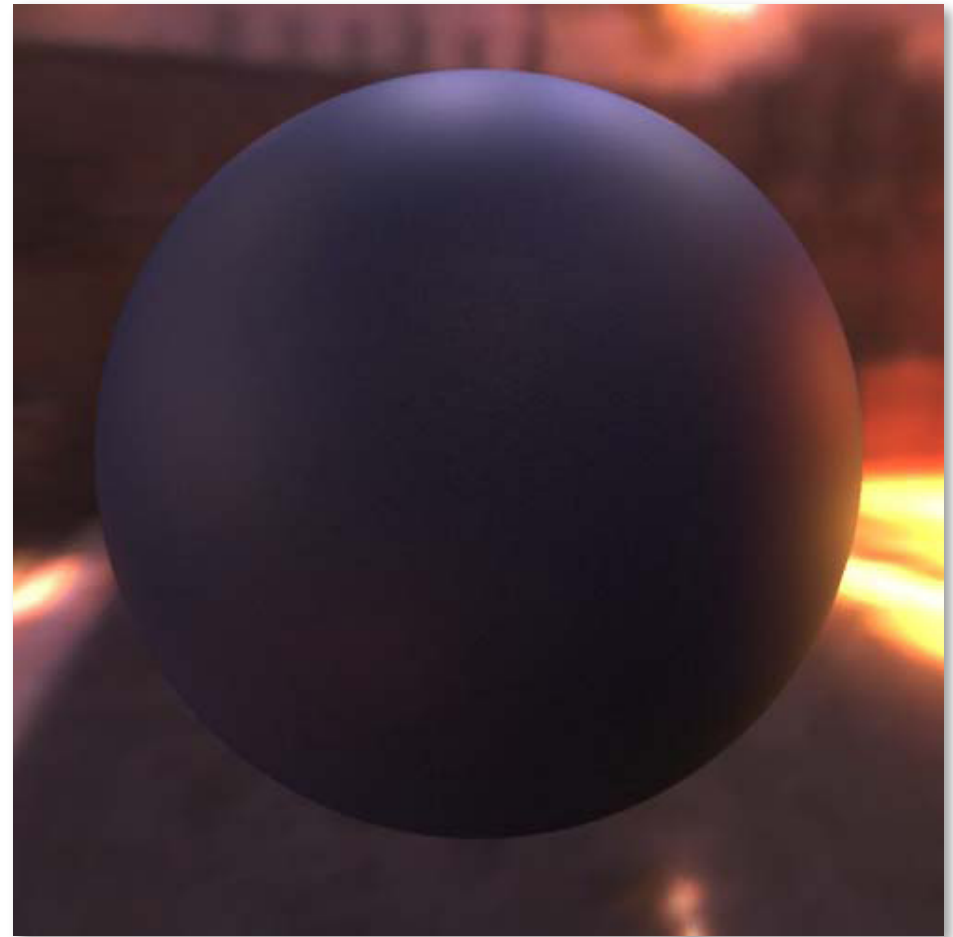


Cook-Torrance-Sparrow Model [1967]

Acquired data

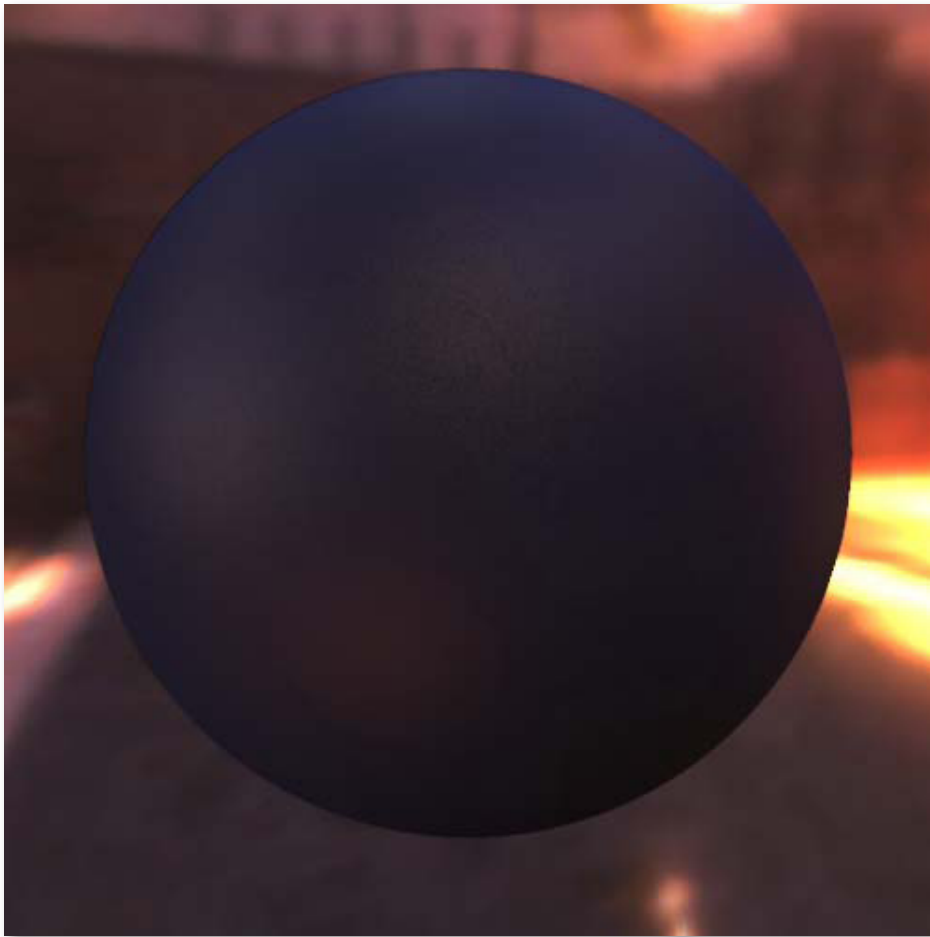


Phong model

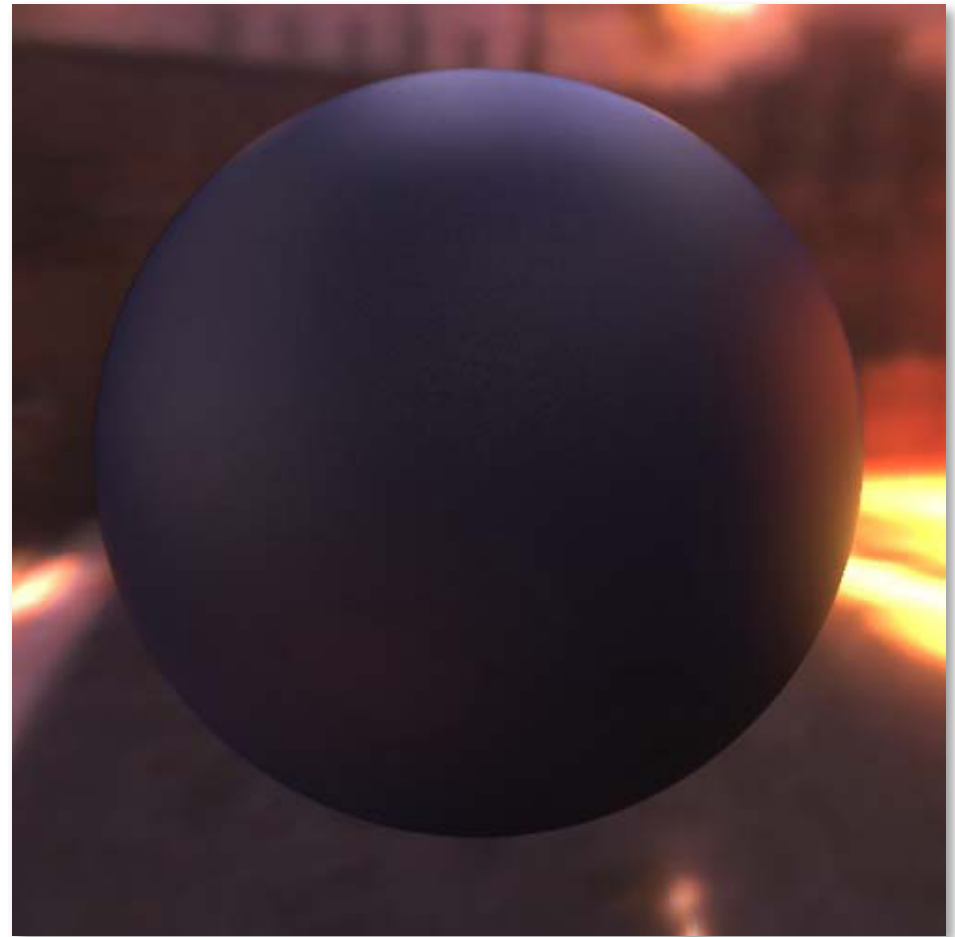


Cook-Torrance-Sparrow Model [1967]

Acquired data

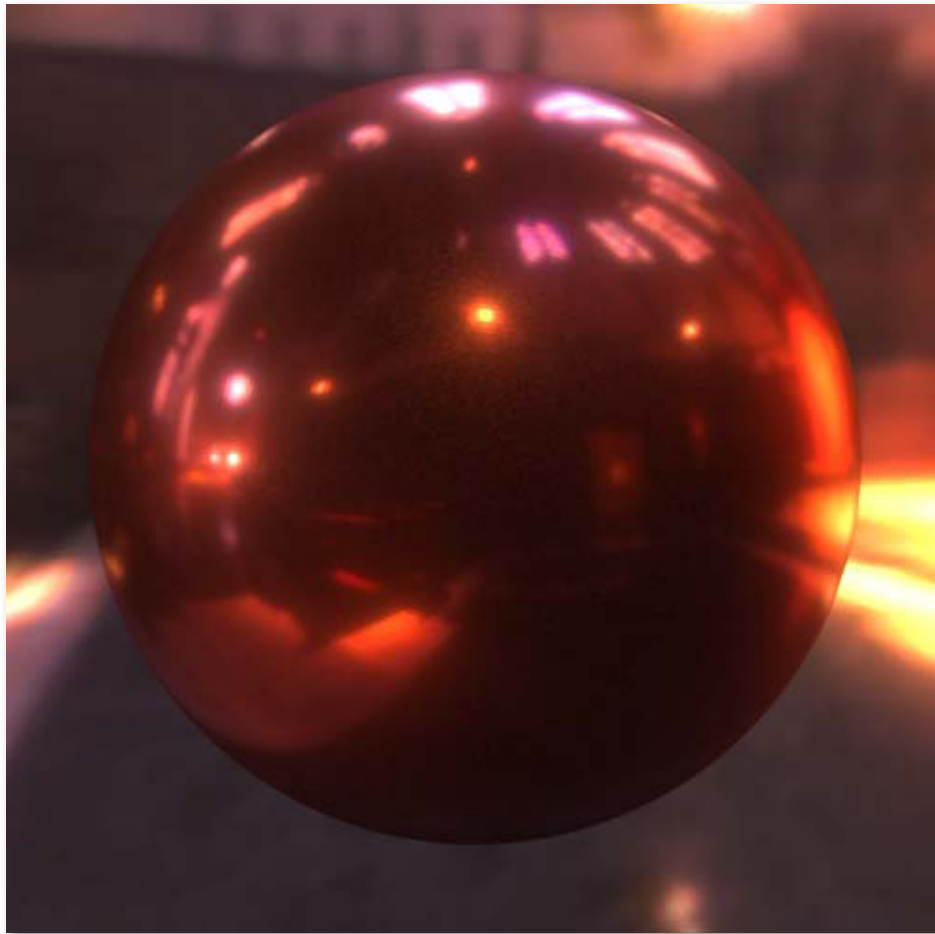


Cook-Torrance model

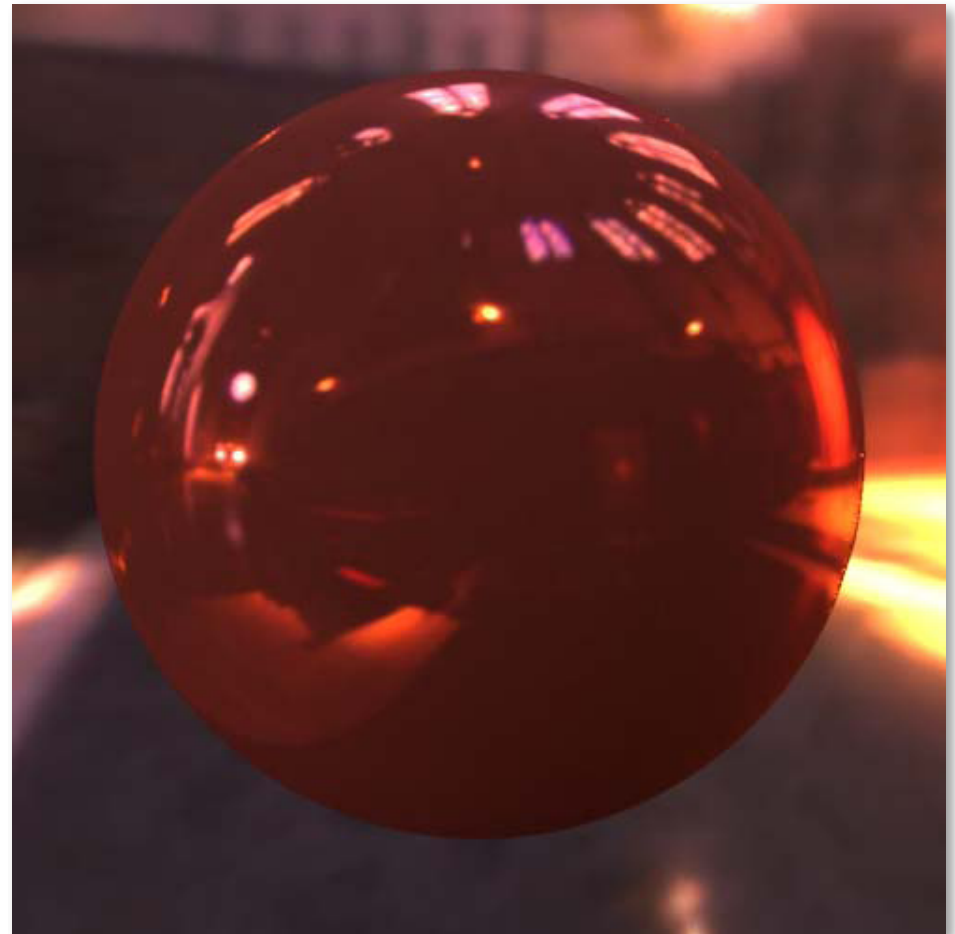


Cook-Torrance-Sparrow Model [1967]

Acquired data

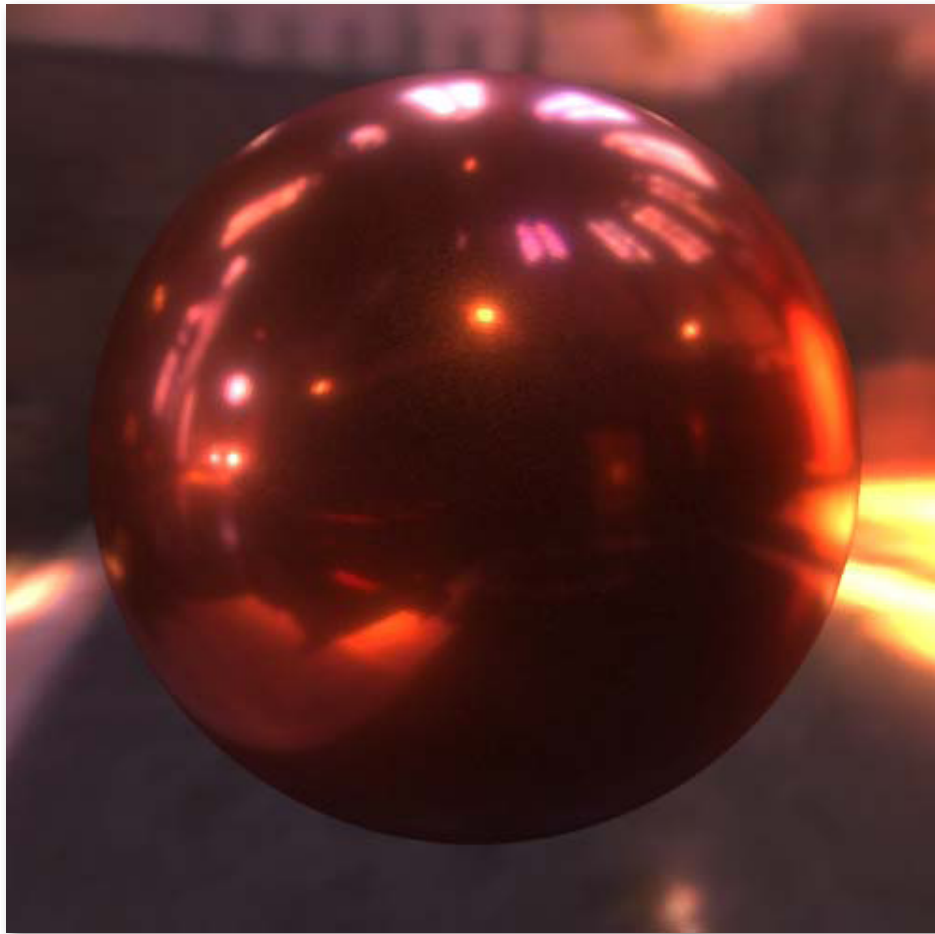


Cook-Torrance model

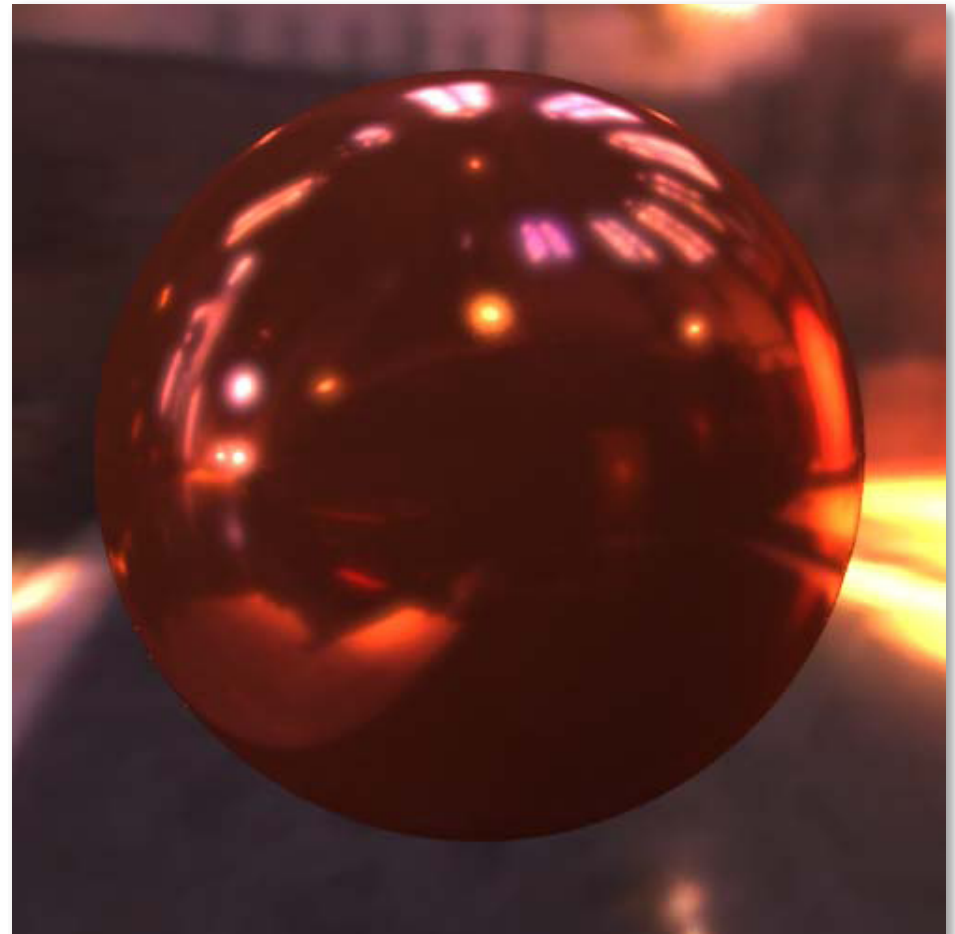


Cook-Torrance-Sparrow Model [1967]

Acquired data



Cook-Torrance, 2 lobes



Spatially varying

- ▶ Map an image on the object surface
= change BRDF parameters at every point
- ▶ Texture mapping



BRDF only



Textured

Spatially varying

- ▶ BTF : Bidirectional Texture Function
 - 6D : 2D in space + 4D for the BRDF
 - Acquisition, compression and editing complex



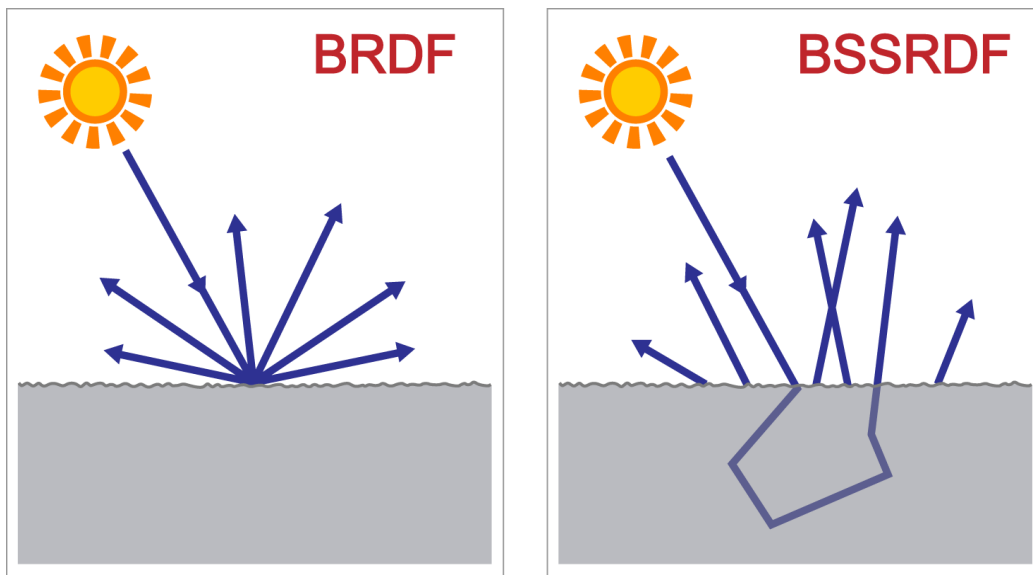
Texture



BTF

Volumetric variations

- ▶ BSSRDF : Bidirectional surface scattering reflectance distribution function
 - 8D function
 - Subsurface Scattering



Ravi Ramamoorthi

Volumetric variations

- ▶ BSSRDF : Bidirectional surface scattering reflectance distribution function



BRDF



BSSRDF

Volumetric variations

- ▶ BSSRDF : Bidirectional surface scattering reflectance distribution function



BRDF



BSSRDF